

# Cala KNX M-T Push Button with Temperature Sensor



Cala KNX M1-T Item numbers 70860 (white), 70862 (black)



Cala KNX M2-T Item numbers 70870 (white), 70872 (black)



Cala KNX M4-T Item numbers 70880 (white), 70882 (black)



# Installation and Adjustment

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1.

2.



Installation, inspection, commissioning and troubleshooting of the device must only be carried out by a competent electrician.

This manual is amended periodically and will be brought into line with new software releases. The change status (software version and date) can be found in the contents footer. If you have a device with a later software version, please check

www.elsner-elektronik.de in the menu area "Service" to find out whether a more up-todate version of the manual is available.

## Clarification of signs used in this manual

$\wedge$	Safety advice.
	Safety advice for working on electrical connections, components, etc.
DANGER!	indicates an immediately hazardous situation which will lead to death or severe injuries if it is not avoided.
WARNING!	indicates a potentially hazardous situation which may lead to death or severe injuries if it is not avoided.
CAUTION!	indicates a potentially hazardous situation which may lead to trivial or minor injuries if it is not avoided.
	! indicates a situation which may lead to damage to property if it is not avoided.
ETS	In the ETS tables, the parameter default settings are marked by underlining.

# 1. Description

The **Cala KNX M-T push button** has touch-sensitive buttons, with which functions in the KNX building bus system can be called, such as switch lights and devices, dim, activate drives, send values, scenarios. An LED is integrated into each touch button, the behaviour of which can be adjusted.

A temperature sensor is integrated into **Cala KNX M-T**. An external temperature reading can be received via the bus and processed with its own data to create a total temperature (mixed value).

Communication objects can be connected by AND and OR logic gates.

The device is supplemented with a frame of the switch series used in the building, and thus fits seamlessly into the interior fittings.

## Cala KNX M1-T functions:

 1 Touch bus button, can be configured as switch, selector switch, dimmer, blind (position and slats up/stop OR down/stop), shutters (up/down/stop), awning (in/out/stop), window (closed/open/stop), as 8 or 16-bit encoder or for scenario recall/storage

### Cala KNX M2-T functions:

- **2 Touch bus button**, can be configured as switch, selector switch, dimmer, for operating drives, as 8 or 16-bit encoder or for scenario recall/storage
- Area function when touching both push buttons. Can be configured as switch, selector switch, as 8 or 16 bit encoder or for scenario recall

### Cala KNX M4-T functions:

- **4 Touch bus button**, can be configured as switch, selector switch, dimmer, for operating drives, as 8 or 16-bit encoder or for scenario recall/storage
- Area function when touching three or more push buttons. Can be configured as switch, selector switch, as 8 or 16 bit encoder or for scenario recall

### Function of all models:

- One LED per touch area. On for object value = 1 / Off for object value = 0, On after pressing button for settable time or always off. Settable, as to whether LED flashes at block object value = 1
- **Temperature** measurements. **Mixed value** from own measured value and external values (proportion can be set by percentage)
- 2 AND and 2 OR logic gates each with 4 inputs. All switching events as well as 8 logic inputs (in the form of communications objects) can be used as inputs for the logic gates. The output from each gate can be configured optionally as 1-bit or 2 x 8-bit

Configuration is made using the KNX software ETS 5. The **product file** can be downloaded from the ETS online catalogue and the Elsner Elektronik website on **www.elsner-elektronik.de** in the "Service" menu.

## 1.0.1. Scope of delivery

- Push button in casing
- Base plate
- Additionally required (not included in the deliverables):
- Junction box Ø 60 mm, 42 mm deep
- Frame (for insert 55 x 55 mm), compatible to the switch scheme used in the building

## 1.1. Technical data

Casing	Genuine glass, plastic
Colours	• similar to RAL 9010 pure white
	<ul> <li>similar to RAL 9005 deep black</li> </ul>
Installation	Flush-mounted (wall installation in junction box $\emptyset$ 60 mm,
	42 mm deep or cavity wall socket for burr hole $Ø$ 68 mm)
IP rating	IP 20
Dimensions	Housing approx. 55 x 55 (W x H, mm),
	Installation depth approx. 10 mm,
	Base plate approx. 71 x 71 (W x H, mm),
Total weight	approx. 50 g
Ambient temperature	Operating -25+80°C, storage -30+85°C
Ambient humidity	max. 95% RH, avoid condensation
Operating voltage	KNX bus voltage
Bus current	max. 15 mA
Data output	KNX +/- Bus plug-in terminal
BCU type	Own microcontroller
PEI type	0
Group addresses	max. 183
Allocations	max. 183
Communication objects	Cala KNX M1-T: 44
	Cala KNX M2-T: 55
	Cala KNX M4-T: 73
Temperature measurement	-25+80°C
range	
Temperature resolution	0.1°C

The product is compliant with the provisions of EU Directives.

## 1.1.1. Accuracy of the measurement

Measurement variations from permanent sources of interference (see chapter *Installation position*) can be corrected in the ETS in order to ensure the specified accuracy of the sensor (offset). When **measuring temperature**, the self-heating of the device is considered by the electronics. The heating is compensated by the software.

# 2. Installation and commissioning

## 2.1. Installation notes

Installation, testing, operational start-up and troubleshooting should only be performed by an electrician.



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#### CAUTION! Live voltage!

There are unprotected live components inside the device.

- National legal regulations are to be followed.
- Ensure that all lines to be assembled are free of voltage and take precautions against accidental switching on.
- Do not use the device if it is damaged.
- Take the device or system out of service and secure it against unintentional use, if it can be assumed, that risk-free operation is no longer guaranteed.

The device is only to be used for its intended purpose. Any improper modification or failure to follow the operating instructions voids any and all warranty and guarantee claims.

After unpacking the device, check it immediately for possible mechanical damage. If it has been damaged in transport, inform the supplier immediately.

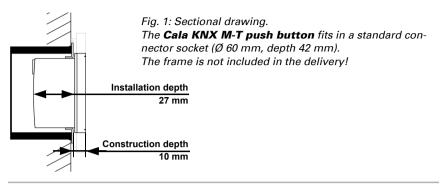
The device may only be used as a fixed-site installation; that means only when assembled and after conclusion of all installation and operational start-up tasks and only in the surroundings designated for it.

Elsner Elektronik is not liable for any changes in norms and standards which may occur after publication of these operating instructions.

## 2.2. Installation location

The **Cala KNX M-T push button** is designed for wall installation in a connector socket (Ø 60 mm, 42 mm deep).

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## May be installed and operated in dry interior rooms only. Avoid condensation.

When selecting an installation location, please ensure that the measurement results are affected as little as possible by external influences. Possible sources of interference include:

- Direct sunlight
- Drafts from windows and doors
- Draft from ducts which lead from other rooms or from the outside to the junction box in which the sensor is mounted
- Warming or cooling of the building structure on which the sensor is mounted, e.g. due to sunlight, heating or cold water pipes
- Connection lines and ducts which lead from warmer or colder areas to the sensor

Measurement variations from permanent sources of interference can be corrected in the ETS in order to ensure the specified accuracy of the sensor (offset).

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## 2.3. Device structure

## 2.3.1. Casing

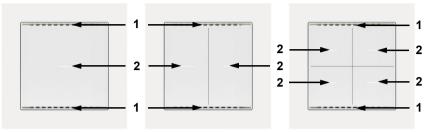


Fig. 2: Front

- 1 Ventilation slit (top and bottom)
- 2 Touch areas with LEDs



Fig. 3: Back

- 1 Base frame
- 2 KNX terminal BUS +/-
- 3 Programming button (recessed) for teaching the device
- 4 Programming LED (recessed)
- 5 Catches

## 2.4. Installation of the sensor

First install the windproof socket with feed line. Seal the inlet tubes as well, in order to prevent draughts.

Then screw the base plate to the socket and place the switch program frame. Connect the bus cable +/- to the plug (black-red).

Insert the device firmly onto the metal frame using the catches so that the device and the housing are fixed together. The device has to be inserted such that the bus terminal faces up (see Fig. 3). This is necessary for a correct temperature measurement and for Cala KNX M2-T and Cala KNX M4-T also for button allocation.

## 2.5. Notes on mounting and commissioning

Never expose the device to water (e.g. rain) or dust. This can damage the electronics. You must not exceed a relative humidity of 95%. Avoid condensation.

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After the bus voltage has been applied, the device will enter an initialisation phase lasting a few seconds. During this phase no information can be received or sent via the bus.

# 3. Addressing of the device at the bus

The device is supplied with the bus address 15.15.255. You can program another address into the ETS by overwriting the 15.15.255 address or by teaching via the programming button.

# 4. Maintenance

Ventilation slits must not be dirty of covered. As a rule, it is sufficient to wipe the device with a soft, dry cloth as required.

# 5. Transfer protocol

## Units:

Temperatures in degrees Celsius

## 5.1. List of all communications objects

#### Abbreviation flags:

- C Communication
- R Read
- W Write
- T Transmit
- U Update

No	Text	Function	Flags	DPT type	Size
0	Software version	Output	R-CT	[217.1] DPT_Version	2 Bytes
Only	with Cala KNX M2-T and Cala KN	NX M4-T			
31	Area operation on/off	Input	-WC-	[1.1] DPT_Switch	1 Bit
32	Area operation Output: Switch	Output	R-CT	depending on setting	2 Bytes
For a	III models				
33	All LEDs On/Off	Input	-WC-	[1.1] DPT_Switch	1 Bit
34	All LEDs Brightness	Input	-WC-	[5.1] DPT_Scaling	1 Byte
35	LED 1 on/off	Input	-WC-	[1.1] DPT_Switch	1 Bit
36	LED 1 Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
Only	with Cala KNX M2-T and Cala KN	NX M4-T			
37	LED 2 on/off	Input	-WC-	[1.1] DPT_Switch	1 Bit
38	LED 2 Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
Only	with Cala KNX M4-T				
39	LED 3 on/off	Input	-WC-	[1.1] DPT_Switch	1 Bit
40	LED 3 Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
41	LED 4 on/off	Input	-WC-	[1.1] DPT_Switch	1 Bit
42	LED 4 Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
For a	III models				
51	Temperature sensor: malfunc- tion	Output	R-CT	[1.1] DPT_Switch	1 Bit
52	Temperature sensor: meas- ured value external	Input	-WCT	[9.1] DPT_Value_Temp	2 Bytes
53	Temperature sensor: meas- ured value	Output	R-CT	[9.1] DPT_Value_Temp	2 Bytes
54	Temperature sensor: meas- ured value total	Output	R-CT	[9.1] DPT_Value_Temp	2 Bytes
55	Temperature sensor: meas- ured value min./max. query	Input	-WC-	[1.17] DPT_Trigger	1 Bit

No	Text	Function	Flags	DPT type	Size
56	Temperature sensor: meas- ured value minimum	Output	R-CT	[9.1] DPT_Value_Temp	2 Bytes
57	Temperature sensor: meas- ured value maximum	Output	R-CT	[9.1] DPT_Value_Temp	2 Bytes
58	Temperature sensor: meas- ured value min./max. reset	Input	-WC-	[1.17] DPT_Trigger	1 Bit
61	Push button 1 long-term	Output	R-CT	[1.8] DPT_UpDown	1 Bit
62	Push button 1 short-term	Output	R-CT	[1.10] DPT_Start	1 Bit
63	Push button 1 switching	Output	R-CT	[1.1] DPT_Switch	1 Bit
64	Push button 1 dimming	Input / Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 Bit
65	Push button 1 encoder 8 bit	Output	R-CT	[5.10] DPT_Value_1_U- count	1 Byte
66	Push button 1 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 Bytes
67	Push button 1 Scene	Output	R-CT	[18.1] DPT_SceneCon- trol	1 Byte
Only	with Cala KNX M2-T and Cala K	NX M4-T			
68	Push button 2 long-term	Output	R-CT	[1.8] DPT_UpDown	1 Bit
69	Push button 2 short-term	Output	R-CT	[1.10] DPT_Start	1 Bit
70	Push button 2 switching	Output	R-CT	[1.1] DPT_Switch	1 Bit
71	Push button 2 dimming	Input / Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 Bit
72	Push button 2 encoder 8 bit	Output	R-CT	[5.10] DPT_Value_1_U- count	1 Byte
73	Push button 2 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 Bytes
74	Push button 2 Scene	Output	R-CT	[18.1] DPT_SceneCon- trol	1 Byte
Only	with Cala KNX M4-T				
75	Push button 3 long-term	Output	R-CT	[1.8] DPT_UpDown	1 Bit
76	Push button 3 short-term	Output	R-CT	[1.10] DPT_Start	1 Bit
77	Push-button 3 switching	Output	R-CT	[1.1] DPT_Switch	1 Bit
78	Push button 3 dimming	Input / Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 Bit
79	Push-button 3 encoder 8 bit	Output	R-CT	[5.10] DPT_Value_1_U- count	1 Byte
80	Push-button 3 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 Bytes
81	Push button 3 Scene	Output	R-CT	[18.1] DPT_SceneCon- trol	1 Byte
82	Push button 4 long-term	Output	R-CT	[1.8] DPT_UpDown	1 Bit
83	Push button 4 short-term	Output	R-CT	[1.10] DPT_Start	1 Bit
84	Push-button 4 switching	Output	R-CT	[1.1] DPT_Switch	1 Bit
85	Push button 4 dimming	Input / Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 Bit

No	Text	Function	Flags	DPT type	Size
86	Push-button 4 encoder 8 bit	Output	R-CT	[5.10] DPT_Value_1_U- count	1 Byte
87	Push-button 4 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 Bytes
88	Push button 4 Scene	Output	R-CT	[18.1] DPT_SceneCon- trol	1 Byte
For a	all models				
91	Logic input 1	Input	-WC-	[1.2] DPT_Bool	1 Bit
92	Logic input 2	Input	-WC-	[1.2] DPT_Bool	1 Bit
93	Logic input 3	Input	-WC-	[1.2] DPT_Bool	1 Bit
94	Logic input 4	Input	-WC-	[1.2] DPT_Bool	1 Bit
95	Logic input 5	Input	-WC-	[1.2] DPT_Bool	1 Bit
96	Logic input 6	Input	-WC-	[1.2] DPT_Bool	1 Bit
97	Logic input 7	Input	-WC-	[1.2] DPT_Bool	1 Bit
98	Logic input 8	Input	-WC-	[1.2] DPT_Bool	1 Bit
101	AND logic 1: 1 bit switching output	Output	R-CT	[1.2] DPT_Bool	1 Bit
102	AND logic 1: 8 bit output A	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
103	AND logic 1: 8 bit output B	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
104	AND logic 1: Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
105	AND logic 2: 1 bit switching output	Output	R-CT	[1.2] DPT_Bool	1 Bit
106	AND logic 2: 8 bit output A	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
107	AND logic 2: 8 bit output B	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
108	AND logic 2: Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
109	OR logic 1: 1 bit switching out- put	Output	R-CT	[1.2] DPT_Bool	1 Bit
110	OR logic 1: 8 bit output A	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
111	OR logic 1: 8 bit output B	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
112	OR logic 1: Block	Input	-WC-	[1.1] DPT_Switch	1 Bit
113	OR logic 2: 1 bit switching out- put	Output	R-CT	[1.2] DPT_Bool	1 Bit
114	OR logic 2: 8 bit output A	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
115	OR logic 2: 8 bit output B	Output	R-CT	[5.010] DPT Value_1_Ucount	1 Byte
116	OR logic 2: Block	Input	-WC-	[1.1] DPT_Switch	1 Bit

# 6. Setting the parameters

# 6.1. Behaviour on power failure/ restoration of power

#### Behaviour following a failure of the bus power supply:

The device sends nothing.

#### Behaviour on bus restoration of power and following programming or reset:

The device sends all outputs according to their send behaviour set in the parameters with the delays established in the "General settings" parameter block.

## 6.2. General settings

Set the basic properties of the data transmission.

Transmission delay after reset/bus restora- tion	<u>5 s</u> • • 300 s
Maximum message rate	<ul> <li>1 message per second</li> <li></li> <li>10 messages per second</li> <li></li> <li>50 messages per second</li> </ul>

## 6.3. Temperature measured value

Select, whether a **malfunction object** is to be sent if the sensor is faulty.

Use malfunction object	No • Yes
···· · · · · · · · · · · · · · · · · ·	

Use **Offsets** to adjust the readings to be sent.

Offset in 0.1°C	-5050; 0

The unit can calculate a **mixed value** from its own reading and an external value. Set the mixed value calculation if desired. If an external portion is used, all of the following settings (threshold values, etc.) are related to the overall reading.

Use external measured value	<u>No</u> •Yes
Ext. Reading proportion of the total reading	5% • 10% • • <u>50%</u> • • 100%
Sending pattern for internal and total measured value	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>

At and above change of ( <i>if sent on change</i> )	0.1°C • 0.2°C • <u>0.5°C</u> • • 5.0°C
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

The **minimum and maximum readings** can be saved and sent to the bus. Use the "Reset temperature min/max. value" objects to reset the values to the current readings. The values are not retained after a reset.

Use minimum and maximum value <u>No</u> • Yes		
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## 6.4. Push button

On Cala KNX M2-T and Cala KNX M4-T there is a screen control with an additional function. It is activated by simultaneously touching two (Cala KNX M2-T) or three or four (Cala KNX M4-T) push buttons. The value of the activation object and the function is set for the screen control.

Set whether you want to use the screen control.

Use screen control	<u>No</u> • Yes
Use screen control	Yes
Activation object assessment	• Value 1 = active   Value 0 = inactive • Value 0 = active   Value 1 = inactive
Object value after reset	0 • <u>1</u>
Function	• <u>Switch</u> • Selector switch • 8 bit value 0 255 • 8 bit value 0 100% • 16-bit floating point value • Scenario recall
Value ( <i>switch</i> )	0 • <u>1</u>
Value (8 bit value 0 255)	0 • • <u>255</u>
Value (8 bit value 0 100%)	0 • • <u>100</u>
Value in 0.1 (16 bit value floating point)	-6707600 • • 6707600; <u>10</u>
Scenario number(Scenario recall)	<u>1</u> ••64

Enable the push button The menus for the other settings of the push buttons are shown on them.

Use push button 1 (top left)	<u>No</u> •Yes
Use push button 2 (top right)	<u>No</u> •Yes
Use push button 3 (bottom left)	<u>No</u> •Yes
Use push button 4 (bottom right)	<u>No</u> • Yes

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## 6.4.1. Push button 1 / 2 / 3 / 4

Set the function of the push button.

Function	<ul> <li>Switch</li> <li>Selector switch</li> <li>Blind</li> <li>Shutters</li> <li>Awning</li> <li>Windows</li> <li>Dimmer</li> <li>8-bit encoder</li> <li>16-bit encoder</li> <li>Scenario recall/ Scenario storage</li> </ul>
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#### Push button as switch

Specify which value is sent when pressing/holding the push button and when.

Function	Switch
Command when pressing the button	O Send
	• 1 Send
	<ul> <li>Do not send message</li> </ul>
Command when releasing the button	O Send
	• 1 Send
	<ul> <li>Do not send message</li> </ul>
Send value	<ul> <li>If there is a change</li> </ul>
	• on change to 1
	• on change to 0
	<ul> <li>on change and periodically</li> </ul>
	<ul> <li>on change to 1 and periodically</li> </ul>
	<ul> <li>on change to 0 and periodically</li> </ul>
Cycle (if transmission is "cyclical")	5 s • • <u>1 min •</u> • 2 h

#### Push button as selector switch

Specify whether a switch is performed when pressing or holding and whether there is an additional function after holding the push button for a long period.

Function	Selector switch
Use additional function for button held down	<u>No</u> •Yes
Use additional function for button held down	No
Command when pressing the button	Switch     Do not send message
Command when releasing the button	Switch     Do not send message

Use additional function for button held down	Yes
Time between tap and hold (0.1 sec)	0 50; <u>10</u>
Command when pressing the button	Do not send message
Command when releasing before time expires	Switch     Do not send message
Command when pressing the button	<ul> <li>0 Send</li> <li>1 Send</li> <li>Switch</li> <li>Do not send message</li> </ul>
Command when releasing the button	<ul> <li>0 Send</li> <li>1 Send</li> <li>Switch</li> <li>Do not send message</li> </ul>
Send value	<ul> <li>If there is a change</li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Transmission cycle (if cyclically sent)	5 s • <u>10 s</u> • • 2 h

#### Push button as blind, shutter, awning or window control

Specify the push button function and the control mode.

Function	Blind / shutters / aw	ning / window
Command (button function)	Up • Down Up • Down • Up/Down Retract • Extend • Retract/Extend Open • Close • Open/ Close	(Blind) (Shutters) (Awning) (Window)
Control mode*	• <u>Standard</u> • Standard inverted • Comfort mode • Dead man switch	

\* For additional setting details, see 💷 "Control modes for drive control" on page 17

### Push button as dimmer

If the push button should be used as a dimmer, select the function "Dimmer" and define the push button function, time interval (switching/dimming) and if required, the repeat interval for extended pressing of the push button.

Command	• <u>Brighter</u> • Darker • Lighter/Darker
Time between switching and dimming (in 0.1 s)	0 50; <u>5</u>
Repeat the dim command	<u>No</u> •Yes
Repeat the dim command with a long hold of the button	every 0.1 s • • <u>every 0.5 s</u> • • every 2 s
Dim by	100% • • <u>6% </u> • • 1.5%

#### Push button as 8 bit encoder

If the push button is to be used as an 8-bit encoder, select the function "8-bit encoder" and define which value is to be transmitted.

Range	• <u>0</u> 255 • <u>0</u> % 100% • <u>0</u> ° 360°
Value	• <u>0</u> 255 • <u>0</u> 100 • <u>0</u> ° 360°

#### Push button as 16 bit encoder

If the push button is to be used as a 16-bit encoder, select the function "16-bit encoder" and define which value is to be transmitted.

Value (in 0.1)	-6707600 6707600; <u>0</u>
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#### Push button as scenario control

If a scenario is to be recalled and saved with a push button, select the "Recall scenario / Save scenario" function and specify whether the push button should also be used to save the scenario (press longer)

Scenario (0-63, corresponds to scenario no. 1-64)	<u>0</u> 63
Scenario function	Call up • Call up and storage
Press button longer than (in 0.1s) > Scenario memory (for call up and storage)	0 <u>50</u>

## 6.4.2. Control modes for drive control

	short:	hold
Blind	Stop/Step	Up or down
Shutters	Stop	Up or down
Awning	Stop	In or out
Windows	Stop	Closed or open

### Behaviour on button actuation in standard control mode:

#### Standard:

If briefly operated, the drive will move incrementally or stops. If operated longer, the drive will move up to the end position. The time difference between "short" and "long" is set individually.

Control mode	Standard
Behavior during button operation: short = stop/increment long = Up or Down	
Time between short and long in 0.1 seconds	150; <u>10</u>

#### Standard inverted:

When pushed shortly, the drive moves up to the end position. When pushed for longer, the drive moves incrementally or stops. The time difference between "short" and "long" and the repeat interval is set individually.

Control mode	Standard inverted
Behavior during button operation: short = Up or Down long = Stop/Step	
Time between short and long in 0.1 seconds	150; <u>10</u>
Repeat the step command for a long button press	every 0.1 s • every 2 sec; every 0.5 sec

#### **Comfort mode:**

In the **comfort mode** actuating the button briefly, a bit longer and long will trigger different responses of the drive. The time intervals are set individually.

**Short actuation** (shorter than Time 1): The drive is positioned step-wise and stopped. **Holding it slightly longer** (longer than Time 1, but shorter than Time 1+2): Drive running. Drive stops when the button is released.

**Long holding** (release after Time 1+2 runs out): Drive moves independently to the end position. The movement can be interrupted by a short tap.

### Fig. 4 Time interval comfort mode diagram

Time 1 Time 2	
0 1	1 + 2
Point in time 0:	Actuate of button, start of time 1
Release before time 1 expired:	step (or stop if drive is moving)
Point in time 1:	End of time 1, start of time 2 Moving command
Release after time 1 expired	
but before time 2 expires:	Stop
Release after time 1 + 2 expired:	Move into end position
Control mode	Comfort mode
Behavior during button operation: Button is pushed and released before time 1 expired = stop/step held longer than time 1 = Up or Down released between time 1 and 1-2= stop released after time 1 +2 = no more stop	
Time 1	0.0s • 2 s; <u>0.4 s</u>
Time 2	0 s • 2 s; <u>2 s</u>

#### Dead man's switch:

The drive moves as soon as the button is actuated and stops as soon as the button is released.

Control mode	Dead man's switch
Behavior during button operation: Push button = Up or Down command Release button = Stop command	

## 6.5. LEDs

Set the LED mode.

LED mo	de	All LEDs off
		<ul> <li>All LEDs as ambient lighting</li> <li>All LEDs individually controllable</li> </ul>
		• All LEDS mulvidually controllable

## All LEDs as ambient lighting

If all LEDs are to be used as ambient lighting, illuminate all simultaneously. Set the brightness of the LEDs, whether objects are used and whether the LEDs switch off automatically after pushing the button.

LED mode	All LEDs as ambient lighting
Brightness	0 100%; <u>30%</u>

Use objects	<u>No</u> •Yes
Object value on/off after reset ( <i>if objects are used</i> )	0 • <u>1</u>
Use automatic switch-off after pressing a button	No • <u>Yes</u>
Switch off after (is automatic switch off is used)	1 255; <u>30 secs. after pressing</u>

#### All LEDs individually controllable

This is where you set the brightness of the LEDs, whether objects are used and whether the LEDs switch off automatically after pushing the button.

LED mode	All LEDs individually controllable
Brightness	0 100%; <u>30%</u>
Use objects	<u>No</u> •Yes
Object value on/off after reset ( <i>if objects are used</i> )	0 • <u>1</u>
Function LED 1 (top left) / 2 (top right) / 3 (bottom left) / 4 (bottom right)	<ul> <li>always OFF</li> <li><u>On after pressing button for settable time</u></li> <li>On for object value = 1 / Off for object value = 0</li> </ul>
Lighting period after pressing ( <i>if "On after pressing button for a settable time"</i> )	1 5 seconds ; <u>3 seconds</u>
Object value after reset ( <i>if</i> "On for object value = 1 / Off for object value = 0)	0 • <u>1</u>
Use block object ( <i>if "On for object value = 1</i> / <i>Off for object value = 0</i> )	<u>No</u> •Yes

## 6.6. Logic

The device has 8 logic inputs, 2 AND and 2 OR logic gates.

Activate the logic inputs and assign object values up to 1st communication.

Use logic inputs	Yes • <u>No</u>
Object value prior to 1st communication for	
- Logic input 1 8	<u>0</u> •1

Activate the required logic outputs

## **AND** logic

AND logic 1/2	not active • active
---------------	---------------------

## **OR** logic

OR logic 1/2	not active • active
--------------	---------------------

## 6.6.1. AND logic 1+2 and OR logic outputs 1+2

The same setting options are available for AND and OR logic.

Each logic output may transmit one 1-bit or two 8-bit objects. Determine what the out put should send if logic = 1 and = 0.

1. / 2. / 3. / 4. Input	Do not use     Logic inputs 18     Logic inputs 18 inverted     Temperature sensor malfunction ON     Temperature sensor malfunction OFF
Output type	• <u>a 1-bit-object</u> • sends two 8-bit objects

If the output type is a 1-bit object, set the output values for the various conditions.

Output value if logic = 1	<u>1</u> •0
Output value if logic = 0	1 • <u>0</u>
Output value If block active	1 • <u>0</u>
Output value if monitoring time exceeded	1 • <u>0</u>

If the **output type is two 8-bit objects**, set the type of object and the output values for the various conditions.

Object type	• value (0255) • Percent (0100%) • Angle (0360°) • Scene call-up (063)
Output value object A if logic = 1	0 255 / 100% / 360° / 63; <u>1</u>
Output value object B if logic = 1	0 255 / 100% / 360° / 63; <u>1</u>
Output value object A if logic = 0	0 255 / 100% / 360° / 63; <u>0</u>
Output value object B if logic = 0	0 255 / 100% / 360° / 63; <u>0</u>
Output value object A If block active	0 255 / 100% / 360° / 63; <u>0</u>
Output value object B If block active	0 255 / 100% / 360° / 63; <u>0</u>
Output value object A if monitoring time exceeded	0 255 / 100% / 360° / 63; <u>0</u>
Output value object B if monitoring time exceeded	0 255 / 100% / 360° / 63; <u>0</u>

Set the output send pattern.

Transmission behaviour	<ul> <li>on change of logic</li> <li>on change of logic to 1</li> <li>on change of logic to 0</li> <li>on change of logic and periodically</li> <li>on change of logic to 1 and periodically</li> <li>on change of logic to 0 and periodically</li> <li>on change of logic + object receipt</li> <li>on change of logic + object receipt</li> <li>and cyclically</li> </ul>
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

## Block

If necessary, activate the block for the logic output and set what a 1 or 0 at the block input means and what happens in the event of a block.

Use block	No • Yes
Assessment of the block object	At value 1: block   At value 0: release     At value 0: block   At value 1: release
Blocking object value before first Commu- nication	<u>0</u> •1
Output behaviour when blocking	Do not send message     Send block value [see above,     output value if block active]
when released (with 2 second release delay)	[send value for current logic status]

## Monitoring

If necessary, activate the input monitoring. Set which inputs are to be monitored, at which intervals the inputs are to be monitored and what value the "monitoring status" should have, if the monitoring period is exceeded without a feedback being given.

Use input monitoring	<u>No</u> •Yes
Input monitoring	•1•2•3•4
	$\bullet 1 + 2 \bullet 1 + 3 \bullet 1 + 4 \bullet 2 + 3 \bullet 2 + 4 \bullet 3 + 4$ $\bullet 1 + 2 + 3 \bullet 1 + 2 + 4 \bullet 1 + 3 + 4 \bullet 2 + 3 + 4$
	•1+2+3+4
Monitoring period	5 s • • 2 h; 1 min
Output behaviour on exceeding the moni-	Do not send message
toring time	<ul> <li>Send value exceeding [= value of the</li> </ul>
	parameter "Monitoring period"]

## 6.6.2. OR LOGIC connection inputs

The OR logic connection inputs are the same as those for the AND logic. Additionally, the following inputs are available for the OR logic:

Switching output AND logic 1 Switching output AND logic 1 inverted Switching output AND logic 2 Switching output AND logic 2 inverted



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